Get real-time vessel information on portable displays and meeting the requirements set by the Panama Canal Authority for the most critical ship-handling needs:

Real time vessel information on display with ECS



Docking





Navigation







Route **Planning**

Path Prediction

Situational Awareness

Fully independent systems are used by many industries and customers world-wide. Some of these are:

- Australian Defence Force, Australia
- New Zealand Defence Force, New Zealand - Royal Navy, United Kingdom
- Royal Australian Navy, Australia
- Gladstone Ports Corporation, Australia
- Sabine Pilots, Texas, USA
- Maranhão Pilots, Sao Luis, Brazil
- Port of Dover, United Kingdom

Navicom's Fixed & Portable systems are used by many industries and customers world-wide. Some of these are:

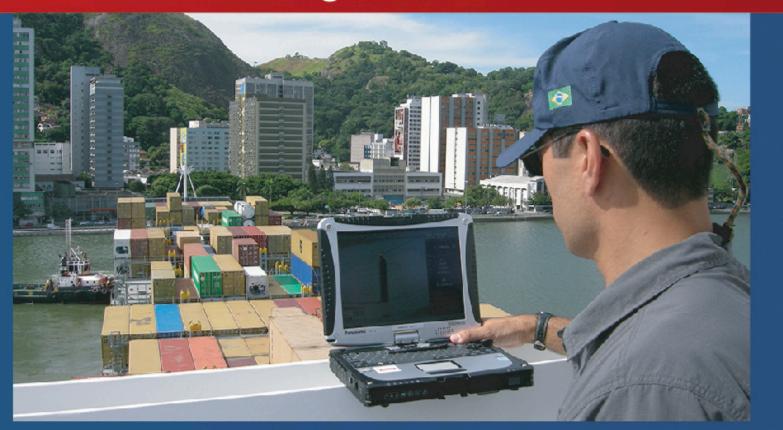
- -FSO Liberdade, Conoco Philips, Australia
- FPSO Pyrenees, BHP Billiton, Australia
- FPSO OKHA, Woodside Energy, Australia
- Mundra SPM, HMPL, India
- Mangalore SPM, MRPL, India
- FPSO Peregrino, Statoil, Brazil
- FPSO John Agyekum Kufuor, Konsberg Eni & Yinson, Ghana
- FPSO Sanha LPG, Chevron, Angola

The Royal Navy







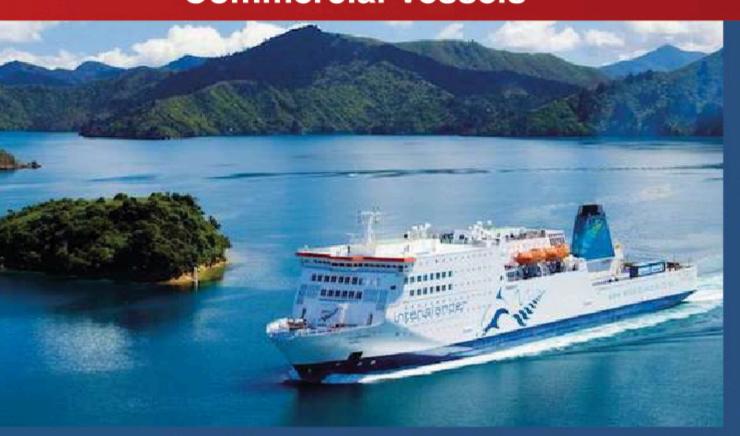


Ships pilots receive accurate data on portable displays

Offshore Oil and Gas operations







A fixed installation on the server rack on Banyu Urip FPSO

HarbourPilot Fixed for the Interislander Ferry Services

sales@navicomdynamics.com | www.navicomdynamics.com |

Office Address: 2 Parkhead Place, Albany, Auckland, NZ 0632. Postal Address: PO Box 302 193, North Harbour, Auckland, NZ 0751.

Follow us on: (1) (in)





CanalPilot

Total situational awareness, at your fingertips.

Navicom Dynamics' Precision Navigation system, the CanalPilot, is the ultimate tool for total situational awareness to ensure safe navigation of vessels through the Panama Canal.

Receive accurate and real-time vessel dynamics information on any number of screens to equip the vessels' navigational crew and key personnel and synchronise operations and communication.

CanalPilot is user-friendly and becomes a familiar secondary source of reliable and accurate information which is independent of the ships' navigational systems.

Facilitate critical decision making during ship-handling and improve safety of crucial manoeuvres with the CanalPilot. Easily add-on shore based data from a server to enhance the information modules to include weather, tides, DUKC and other critical data to support navigation.

It acts as a fall back navigational system that can optionally include battery back-up to provide a totally independent navigational tool in case all else fails.



A completely independent mGNSS enabled dual antenna system.



mGNSS Antennas



Performance Features & Usability

Independent of vessel

The system is entirely independent of the vessel. It is a secondary source of vital vessel information that supports critical decision-making during manoeuvres.

Critical information source/data points

Get accurate Position, Heading, Rate-of-turn, COG, SOG and other useful data to create to create a stable image of the vessel on the chart display software with optional future vessel path predictions.

Situational awareness

Increased situational awareness of the vessel and it's surroundings made available on as many displays as required (to equip entire crew).

Portability

Information available on portable displays (tablets/iPads), allows the crew to easily walk around the bridge wing or any location that has been set up.

Extendibility

Add-on any number of screens to interface with CanalPilot to provide the same accurate & real-time information to additional crew members for a synchronised operation. Add-on shore based data points from a server to the software appear as integrated information to the user (with the original data points from the PPU)

Premium Quality

High quality sensors with advanced technology to form state-of-the-art systems that are accurate, reliable and user-friendly.

User-oriented, feature-rich software

A number of useful features to improve training, usability, safety and for personal enhancement.

CanalPilot - Product Specifications

Physical Specifications

Dimensions & Weight Power requirements

186 x 81 x 250mm (WxHxD) | 3.5 kg

Battery back-up > 8

90-240 VAC / 24 VDC 15W > 8 hours of operation

Indicators

Mode, Corrections, Heading, GNSS, Battery, WiFi, AIS, UHF, LTE

External Interfaces

GNSS Antennas x2 UHF Antenna VHF Antenna

Wi-Fi Antenna

RoHs

TNC Jack N Jack

SO239 Jack (mates to PL259)

RP-SMA Jack

USB (device only) Mains power DC power

USB Type B 3-pin IEC C14 Inlet 2-pin Terminal Block w Screw Lock

Environmental Specifications

Operating Temperature Storage Temperature Humidity -20°C to +74°C (-4°F to +165°F) -40°C to +85°C (-40°F to +185°F)

95% (non-condensing)

CanalPilot meets the directive for Restriction of Hazardous substances

Whats Included

Navicom Dynamics CanalPilot (1 no) | GNSS Antenna (L1/L2/L5) (2 nos) | VHF Antenna (162 MHz) (1 no) UHF Antenna (454.325 MHz) (1 no) | Coaxial Cable 120m Antenna Mounting brackets (4 nos)

Technical Specifications

GNSS Antenna

Signals Received

Enclosure Rating

Shock/Vibration

LNA Gain

LNA Noise

GPS L1/L2/L5, GLONASS G1/G2, BeiDou B1/B2/B3, SBAS, L-band, Galileo F1/F5a and b

L1C/A, L2C, L1OF, L2OF, E1, E1B/C, E5b, B1l, B2l

GPS, QZSS, Galileo, GLONASS, BeiDou

RTK: 0.008m +/s 1ppm, SBAS: 0.3m

HDG Accuracy: 0.02° (5m baseline)

L-band, Galileo E1/E5a and b 30 dBm

2.0 dB, typical IP69K EP455

GNSS Receiver (primary)

Position source (Frequencies)

Tracked systems
Correction source

Position accuracy (RMS) Heading

Rate of Turn Speed accuracy

Anti-jamming

GNSS Receiver (auxilary)
Anti-jamming RF interference and jamming detection and reporting

'Cygus' anti-jamming technology

RTCMv3 (Wifi/ UHF), SBAS

ROT Accuracy: 0.1°/min

Anti-jamming RF interference and jamming det Anti-spoofing Spoofing detection and reporting

0.03 m/s

RTK/DGNSS Corrections

Network DGNSS corrections UHF DGNSS corrections

Using RTCMv3 over Wifi connection (NTRIP: Port 2102)
Using RTCMv3 over UHF connection (454.325 MHz)

IMU (Inertial measurement unit)

IMU Gyro Bias Instability IMU Angular Random Walk Degree of Freedom

1.2°/hr 0.08°/√hr

6 DOF: Triple Gyroscope, Tri-Axis Accelerometer

UHF Antenna (Pre-tuned to 454.325 MHz using TrimTalk 450S to receive RTCMv3 DGNSS corrections)

Frequency
Occupied bandwidth
Modulation type/Protocol

410 – 480 MHz 6.25, 12.5, 25 kHz

GMSK, Trimtalk 450S (+ others on request)

-115 dBm

VHF Antenna

Receiver Sensitivity

Frequency VSWR 162 MHz 1.5:1

AIS Receiver

Dual frequency Receiver Sensitivity 161.975 & 162.025 MHz

ensitivity < -107dBm at 20% packet error rate

Wi-Fi

Access Point
Security
Output power
Receiver Sensitivity

IEEE 802.11 a/b/g/n WPA2

18 EIRP [dBm] < -82dBm

Bluetooth

Output power Receiver Sensitivity 14 EIRP [dBm] < -70dBm

Data / Connectivity

Data output (NMEA/AIS)
Data protocol
Connectivity
UDP Port

GGA, VTG, HDT, ROT, GSA, GSV, VDM, PTMSX, PTMSG NMEA-0183 (compatible with Trelleborg SafePilot) Wi-Fi, Bluetooth, Ethernet (optional) 17608